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Current driven spin-wave instability triggered by the anomalous Hall effect

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We studied the effect of strong electric current on spin waves interacting relativistically with the current. The spin-wave spectrum is calculated at the arbitrary direction of the wave vector. It is shown that the alternating Hall current generated by the alternating magnetic moment of the spin waves reduces the spin-wave damping. At strong enough unpolarized dc current the damping changes sign, and the spin-wave amplitude starts to increase exponentially fast with time. The critical current for the spin-wave instability is determined mainly by the anomalous Hall effect, and can be much smaller than that for the spin-torque mechanism of instability.

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Current-induced switching of the magnetization or spinwave excitation in magnetically inhomogeneous systems, e.g., multilayers, has received considerable attention during the last decade.¹ When a spin-polarized current passes through a ferromagnetic layer, the electrons transfer their spin angular momentum to the localized spins of the ferromagnet resulting in a spin torque acting on the magnetization.^{2,3} The theoretical predictions were confirmed by several groups, the experiments being performed mainly with trilayers of structure ferromagnet–normal-metal– ferromagnet, in which the layer magnetization may be noncollinear; see Ref. 1, and references therein.

It has been argued recently that polarized current can also affect the magnetic properties of a homogeneous bulk ferromagnetic metal.^{4–7} Adding the spin torque linear in the spin current to the Landau-Lifshitz equation of motion, one gets a modified spin-wave (SW) spectrum, which shows a current driven instability. In a half metal, when the density of the minority carriers is zero, the spin current is equal to the electric current. In this case the uniform ferromagnetic state becomes unstable at a critical current given by the relation^{4,5}

$$\mathbf{k} \cdot \mathbf{v}_d = \omega_{\mathbf{k}},\tag{1}$$

where **k** is the spin-wave wave vector, $\omega_{\mathbf{k}}$ is the spin-wave dispersion, and \mathbf{v}_d is the electron drift velocity, which is proportional to the electric current. This "Doppler-shift" critical current is of the order of 10⁹ A/cm² (Ref. 5) but, in general, as has been shown by Tserkovnyak *et al.*,⁷ the critical current can be strongly enhanced.

High enough current densities can excite SW excitations in ferromagnetic layers even when the current is unpolarized, if the source and drain contacts are nonsymmetric.⁸ SW excitation by an unpolarized current injected into a single ferromagnetic film from a point contact was observed by Ji *et* $al.^9$ and considered theoretically in Refs. 10.

The original models by Slonczevski² and Berger³ and all subsequent considerations of current-induced SW excitation rely on the exchange model of interaction between the itinerant electrons and the localized spins. In this paper we concentrate on the electromagnetic (relativistic) interaction of the electron current with the field of the SW, which does not preserve the total spin. We show that in ferromagnetic conductors with large anomalous Hall effect this interaction can lead to current-induced SW instability at critical unpolarized current of the same order or even smaller than that in the exchange interaction models. Unlike the exchange coupling of itinerant electrons with the SW, which is effective only in the vicinity of the interface between normal and ferromagnetic layers,³ the above relativistic interaction acts also in the bulk of the ferromagnet. Therefore, the current-induced SW instability caused by the Hall effect is not restricted to a layered structure of the ferromagnet.

The physical mechanism for SW generation via the relativistic interaction is as follows. Suppose for simplicity that an electric current \mathbf{j}_0 is driven parallel to the magnetization \mathbf{M}_0 . Consider a spin wave propagating along \mathbf{M}_0 . The oscillating magnetic moment and magnetic field of the spin wave lie in the plane perpendicular to \mathbf{j}_0 and \mathbf{M}_0 . This gives rise to an alternating Hall current perpendicular to \mathbf{M}_0 , which in turn creates a magnetic field amplifying the field of the wave. If the electric field is strong enough, the amplification will exceed the damping due to eddy currents. If there are no other sources of damping, the spin-wave system becomes unstable at such field. We show in this paper that the instability is not restricted to the above simple geometry. It takes place at any mutual orientation of \mathbf{j}_0 and \mathbf{M}_0 .

In ferromagnetic metals the main contribution to the Hall current comes from the anomalous Hall effect caused by the spin-orbit coupling in the metal. Since the anomalous Hall constant is by orders of magnitude larger than the normal one, the critical current for SW amplifying can be relatively small.

The full set of equations, which describes SW in a conducting media interacting with an electric current, consists of the Landau-Lifshitz equation and of the Maxwell's equations. The Landau-Lifshitz equation for the precession of the magnetic moment is¹¹

$$\frac{\partial \mathbf{m}}{\partial t} = \gamma \mathbf{M}_0 \times \mathbf{H}_{\text{eff}} + \frac{1}{\tau_2} \mathbf{H}_{\text{eff}} - \frac{1}{\tau_1 M_0^2} \mathbf{M}_0 \times (\mathbf{M}_0 \times \mathbf{H}_{\text{eff}}).$$
(2)

Here **m** is the (small) transverse alternative part of the magnetization $m \ll M_0$, γ is the gyromagnetic ratio, τ_1 and τ_2 are phenomenological SW relaxation times, and **H**_{eff} is the effective magnetic field given by

$$\mathbf{H}_{\rm eff} = \mathbf{h} + \left[\frac{D}{\gamma M_0} \nabla^2 - \frac{\mathbf{m}_0 \cdot \mathbf{H}_0}{M_0} - K(\mathbf{m}_0 \cdot \mathbf{n})^2 \right] \mathbf{m} + K \mathbf{n} (\mathbf{n} \cdot \mathbf{m}),$$
(3)

where **h** is the alternative part of the magnetic field, D is the stiffness constant of the SW, \mathbf{H}_0 is the external magnetic

field, which in restricted samples includes also the demagnetizing fields, \mathbf{n} and \mathbf{m}_0 are unit vectors directed along the anisotropy axis and the magnetization, respectively, and *K* is the dimensionless anisotropy constant.

The Maxwell equations are

$$\nabla \times \mathbf{h} = \frac{4\pi}{c} \mathbf{j},$$
$$\nabla \times \mathbf{e} = -\frac{1}{c} \frac{\partial \mathbf{b}}{\partial t},$$
$$\nabla \cdot \mathbf{b} = 0.$$
(4)

Here the alternating magnetic induction is $\mathbf{b}=\mathbf{h}+4\pi\mathbf{m}$, **e** is the alternating electric field, *c* is the light velocity, and **j** is the alternating electric current given by¹²

$$\mathbf{j} = \sigma \mathbf{e} + \sigma (R_B \mathbf{j}_0 \times \mathbf{b} + R_M \mathbf{j}_0 \times \mathbf{m}), \qquad (5)$$

where R_B and R_M are the ordinary and anomalous Hall coefficients, respectively, σ is the conductivity, and \mathbf{j}_0 is the dc part of the electric current density. We neglected in Eqs. (4) the displacement current, since for conductors considered here the inequality $\omega \ll \sigma$ always holds. We skipped in Eq. (5) a small term of order $\sigma(R_B B_0 + R_M M_0) \ll 1$. The SW frequences considered in the paper are of order of $(10^9 - 10^{10}) \text{ s}^{-1}$, i.e., much smaller than all typical electron relaxation frequencies in a ferromagnetic metal. Therefore, we used below the dc values of the transport coefficients.

The Maxwell equations, with the current from Eq. (5), relate the Fourier transforms of **h** and **m** as

$$\mathbf{h} = -4\pi \left[\omega_0 k^2 + i \frac{2}{\delta^2} (\mathbf{k} \cdot \mathbf{v}_b - \omega) \right]^{-1} \left[\omega_0 (\mathbf{k} \cdot \mathbf{m}) \mathbf{k} - i \frac{2}{\delta^2} (\mathbf{k} \cdot \mathbf{m}) \mathbf{v}_m - i \frac{2}{\delta^2} (\omega - \mathbf{k} \cdot \mathbf{v}) \mathbf{m} \right].$$
(6)

Here $\omega_0 = 4\pi\gamma M_0$, the skin penetration depth δ at frequency ω_0 is given by $\delta = (c^2/2\pi\sigma\omega_0)^{1/2}$, and the effective velocities \mathbf{v}_b , \mathbf{v}_m , and \mathbf{v} are related to the Hall coefficients by

$$\mathbf{v}_b = R_B c \mathbf{j}_0 \equiv \mathbf{v}_d, \quad \mathbf{v}_m = \frac{R_M c \mathbf{j}_0}{4\pi}, \quad \mathbf{v} = \mathbf{v}_b + \mathbf{v}_m. \tag{7}$$

It is supposed that δ is much larger than the electron mean free path.

The Landau-Lifshitz equation yield another relation between **h** and **m**. When \mathbf{H}_0 and \mathbf{M}_0 are parallel and directed along the anisotropy axis, this relation reads

$$(\Omega_{\mathbf{k}} - \omega - i\alpha\Omega_{\mathbf{k}})m_{+} = \gamma M_{0}h_{+}(1 - i\alpha),$$

$$(\Omega_{\mathbf{k}} + \omega + i\alpha\Omega_{\mathbf{k}})m_{-} = \gamma M_{0}h_{-}(1 + i\alpha).$$
(8)

Here

$$\alpha = \frac{1}{\gamma M_0} \left(\frac{1}{\tau_1} + \frac{1}{\tau_2} \right),\tag{9}$$

 $m_{\pm}=m_x \pm im_y$, $h_{\pm}=h_x \pm ih_y$, while the axis z is along the magnetization. The frequency Ω_k is given by

$$\Omega_k = \gamma (H_0 + H_a) + Dk^2, \tag{10}$$

where H_a is the anisotropy field $H_a = KM_0$.

Equations (6) and (8) give the dispersion relation for SW in an external electric field. We consider in what follows wave vectors k, which are larger than δ^{-1} : $k\delta \ge 1$. Then to leading order in the small parameter $1/k^2\delta^2$ one obtains

$$\begin{aligned} {}^{2}_{\mathbf{k}}(j_{0}) &= \Omega_{\mathbf{k}} \Omega_{1\mathbf{k}} + \frac{2\omega_{\mathbf{k}}(0)}{\delta^{2}k^{2}} (\mathbf{k} \times \mathbf{v}_{m}) \cdot \mathbf{m}_{0} - i \\ &\times \left\{ \frac{2}{\delta^{2}k^{2}} (\Omega_{1\mathbf{k}} + \Omega_{\mathbf{k}}\cos^{2}\theta) [\omega_{\mathbf{k}}(0) - \mathbf{k} \cdot \mathbf{v}] \right. \\ &+ \alpha\omega_{\mathbf{k}}(0)(2\Omega_{\mathbf{k}} + \omega_{0}\sin^{2}\theta) \right\} \\ &- i \frac{2}{\delta^{2}k^{4}} \Omega_{\mathbf{k}} \mathbf{k} \cdot \mathbf{m}_{0} [(\mathbf{v}_{m} \cdot \mathbf{k})(\mathbf{m}_{0} \cdot \mathbf{k}) - k^{2}\mathbf{v}_{m} \cdot \mathbf{m}_{0}]. \end{aligned}$$
(11)

Here θ is the angle between the wave vector **k** and the magnetization, $\Omega_{1\mathbf{k}} = \Omega_{\mathbf{k}} + \omega_0 \sin^2 \theta$, and $\omega_{\mathbf{k}}(0) \equiv \omega_{\mathbf{k}}(\sigma=0) = \sqrt{\Omega_{\mathbf{k}}\Omega_{1\mathbf{k}}}$. In the absence of the current j_0 , this equation gives the usual spectrum of SW decaying due to Landau-Lifshitz-Gilbert damping α , and due to the eddy currents. The last decay is proportional to $1/k^2 \delta^2$.

In what follows we consider such wave vectors that the contribution to the SW damping from the last term in Eq. (11) is equal to zero. This happens specifically, if **k** is along or perpendicular to the magnetization, or at any θ provided **k** is along the current. Equation (11) then yields

Re
$$\omega_{\mathbf{k}}(j_0) = \sqrt{\Omega_{\mathbf{k}}\Omega_{1\mathbf{k}}} + \frac{(\mathbf{k} \times \mathbf{v}_m) \cdot \mathbf{m}_0}{\delta^2 k^2},$$

Im $\omega_{\mathbf{k}}(j_0) = -(\nu_{\mathbf{k}} + \alpha_{\mathbf{k}}) \left(\omega_{\mathbf{k}}(0) - \frac{\nu_{\mathbf{k}}}{\nu_{\mathbf{k}} + \alpha_{\mathbf{k}}} \mathbf{k} \cdot \mathbf{v} \right).$ (12)

Here

ω

$$\nu_{\mathbf{k}} = \frac{\Omega_{1\mathbf{k}} + \Omega_{\mathbf{k}} \cos^{2} \theta}{k^{2} \delta^{2} \sqrt{\Omega_{\mathbf{k}} \Omega_{1\mathbf{k}}}},$$

$$\alpha_{\mathbf{k}} = \frac{\alpha}{2 \sqrt{\Omega_{\mathbf{k}} \Omega_{1\mathbf{k}}}} (2\Omega_{\mathbf{k}} + \omega_{0} \sin^{2} \theta).$$
(13)

Equation (12) is our main result. It shows that Im ω changes sign at a critical velocity \mathbf{v}_c given by the relation

$$\mathbf{k} \cdot \mathbf{v}_c = \left(1 + \frac{\alpha_{\mathbf{k}}}{\nu_{\mathbf{k}}}\right) \omega_{\mathbf{k}}(0).$$
(14)

At higher effective velocities, i.e., at higher currents the amplitude of spin waves, with \mathbf{k} satisfying Eq. (14), increases exponentially with time.

When $R_M/4\pi$ is smaller than R_B , i.e., $v = v_b = v_d$, the SW instability condition (14) resembles those obtained in Refs. 4–7 for SW instability in half-metals triggered by spin-transfer torques; see Eq. (1). However, R_M in ferromagnetic conductors is usually by many orders of magnitude larger

than R_B . We have, therefore, $v \approx v_m \gg v_d$, and the critical current for the instability considered here is much smaller than the critical current given by Eq. (1).

Measurements¹³ performed on Fe, Co, Ni, and Gd films with the thickness of 1 μ m show that in pure metals, with the resistivity $\rho = (10^{-4} - 10^{-6}) \Omega$ cm, the anomalous Hall conductivity σ_H is of the order $10^3 (\Omega \text{ cm})^{-1}$. Thus, for metals with the resistivity $\rho = (10^{-4} - 10^{-5}) \Omega$ cm, and with $M_0 \approx 10^3$ G, one gets $R_M = (10^{-8} - 10^{-10}) \Omega$ cm/G. The values of R_M for Ni films, which follow from the data obtained in Ref. 14, also fall in this region. It follows then from Eq. (7) that the effective velocity v_m is of the order $v_m = (10^{-1} - 10^{-3})j_0$. Here j_0 is in A/cm², and v_m in cm/s. Note that the typical drift velocity is of the order $10^{-4}j_0$ cm/s.⁵

The real part of the SW frequency (12) also acquires a term linear in the current, which is solely caused by the anomalous Hall effect. The frequency of spin waves, with **k** nonparallel to the magnetization and to the current, is modified by the current. The current increases or decreases the frequency, depending on the direction of **k**.

When the wave vector \mathbf{k} and the current are along the magnetization, the critical velocity is given by

$$v_c(k) = \left[Dk + \frac{\gamma(H_0 + H_a)}{k}\right] \left(1 + \frac{\alpha}{2}\delta^2 k^2\right).$$
(15)

 $v_c(k)$ is minimal at $k=k_0$ given by

$$k_0^2 = \frac{1}{6\alpha\delta^2} [-(2+\alpha\beta) + \sqrt{4+28\alpha\beta + (\alpha\beta)^2}], \quad (16)$$

where $\beta = \gamma (H_0 + H_a) \delta^2 / D$.

When the damping α is small, $\alpha \ll 1/\beta$, the critical velocity coincides with the phase velocity of the SW,¹² and k_0 is given by $k_0 = [\gamma(H_0 + H_a)/D]^{1/2}$, $v_c(k_0)$ being equal to

$$v_c(k_0) = 2\sqrt{D\gamma(H_0 + H_a)}.$$
 (17)

With typical values $D = (0.1 - 0.05) \text{ cm}^2/\text{s}$ and $\gamma(H_0 + H_a) = 2 \times 10^9 \text{ s}^{-1}$, one gets $v_c(k_0) \approx 3 \times 10^4 \text{ cm/s}$. Thus, the minimal critical current density is $j_c = 4\pi v_c(k_0)/R_Mc \approx (3 \times 10^5 - 3 \times 10^7) \text{ A/cm}^2$. This value of j_c is by several orders of magnitude smaller than that obtained in Refs. 5 and 6.

The wave vector k_0 decreases with increase of α . If α is large, $\alpha \ge 1/\beta$, it follows from Eq. (16) that k_0 does not depend on *D* and γH_0 , and is equal to $k_0 = (2/\alpha \delta^2)^{1/2}$. The critical velocity in this case is

$$v_c(k_0) = \delta \gamma (H_0 + H_a) \sqrt{2\alpha}, \qquad (18)$$

increasing linearly with the external magnetic field.

With $\sigma = 10^5 \Omega^{-1} \text{ cm}^{-1}$ and $\omega_0 = 10^{11} \text{ s}^{-1}$, one gets $\delta = 10^{-4} \text{ cm}$. Then, with the above values of D and $\gamma(H_0 + H_a)$ one finds that the inequality $\alpha \ge 1/\beta$ is fulfilled, if α is larger than 10^{-2} . The dependence of the minimal critical velocity on α at different values of the conductivity is shown in Fig. 1.

If \mathbf{k} is parallel to the current and perpendicular to the magnetization, Eqs. (14) and (13) yield



FIG. 1. Dependence of the minimal critical velocity on α at different conductivities $\sigma = (1, 2, 5, 10) \times 10^4 (\Omega \text{ cm})^{-1}$, with parameters $D = 0.1 \text{ cm}^2/\text{s}$, $H_0 + H_a = 100 \text{ Oe}$. Both **k** and **j**₀ are along the magnetization.

$$v_c(k) = \frac{1}{k} \sqrt{\Omega_k(\Omega_k + \omega_0)} \left(1 + \frac{\alpha \delta^2 k^2}{2} \frac{2\Omega_k + \omega_0}{\Omega_k + \omega_0} \right).$$
(19)

Usually the inequality $\gamma H_0 \ll \omega_0$ holds. Then, at small α , $\alpha \ll 1/\beta$, the minimal critical velocity is

$$v_c(k_0) = \sqrt{D\omega_0} \approx 10^5 \text{ cm/s}, \qquad (20)$$

while the minimal critical current is of the order (10^6-10^8) A/cm². As before, the critical velocity increases with increase of α . When α is large, and satisfies the inequality $\alpha \ge 1/\beta$, the minimal critical velocity is

$$v_c(k_0) = 2\delta \sqrt{\gamma(H_0 + H_a)\omega_0 \alpha}.$$
 (21)

The critical velocity and the critical current can be considerably smaller than the above values, if the ferromagnet is in a state close to an orientational phase transition caused by an external magnetic field. We consider now the instability condition in several different arrangements of this type. In all cases we suppose that \mathbf{k} is along the dc current, since we are interested in the minimal critical current.

First, let in a uniaxial ferromagnet the external magnetic field is aligned perpendicular to the easy axis, and H_0 is larger but close to H_a . Then, the magnetization points along \mathbf{H}_0 . Repeating the previous calculation for this orientation of the field, one gets for \mathbf{k} and \mathbf{j}_0 along the magnetization

$$v_c(k) = \frac{\omega_k}{k} \left(1 + \frac{\alpha \delta^2 k^2}{2} \right), \tag{22}$$

where¹¹

$$\omega_{\mathbf{k}} = \sqrt{[Dk^2 + \gamma(H_0 - H_a)](Dk^2 + \gamma H_0)}.$$
 (23)

At small α

and at $H_0 - H_a \ll H_a$, the critical velocity is minimum at a wave vector, given by

$$k_0 = \left[\frac{\gamma^2 H_a (H_0 - H_a)}{D(D + \alpha \delta^2 \gamma H_a)}\right]^{1/4},$$
 (25)

and $v_c(k_0)$ is

$$v_c(k_0) = \sqrt{D \gamma H_a},\tag{26}$$

which is considerably smaller than the critical velocity (17). At large α , $\alpha \ge D / \gamma (H_0 - H_a) \delta^2$, the critical velocity is equal to

$$v_c = \gamma \delta \sqrt{2\alpha H_a (H_0 - H_a)}.$$
 (27)

Note that if $(H_0 - H_a)/H_a$ is small, the inequalities (24) and $k_0^2 \delta^2 \ge 1$ are fulfilled whenever α is smaller than 1, i.e., the SW damping in this case almost does not affect the critical current.

Suppose now that the ferromagnet is in a metastable state, with the field \mathbf{H}_0 smaller than H_a and opposite in direction to the magnetization. It follows then from Eq. (3) that in Eq. (15) and in all subsequent equations for v_c the field H_0 should be replaced by $-H_0$. Hence, when H_0 approaches H_a the critical wave vector and v_c tend to zero. k_0 is restricted from below by the inequality $k_0^2 \delta^2 \ge 1$. This gives for small damping α , which satisfies the inequality (24): $\gamma(H_a - H_0) \ge D \delta^{-2}$, $v_c \ge 2D/\delta \approx 10^3$ cm/s, and $j_c \ge 10^4$ A/cm². This implies that a relatively small current of order or larger than $(3-5) \times 10^4$ A/cm² can drive the magnetization switching at magnetic fields smaller than H_a , if the current flows along the magnetization. Note that, as in the previous case, the inequality (24) is equivalent to the condition $\alpha \ll 1$.

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Finally, consider thin films, with $kd \le 1$; d is the film width. The SW spectrum in this case at different directions of the magnetization and external magnetic field was derived in many papers; see, e.g., Refs. 15. We consider the case when the external magnetic field is perpendicular to the film plane and larger than $4\pi M_0 + H_s - H_a$, where H_a is the volume anisotropy field, the easy axis being in a symmetry direction of the film, and H_s is the surface anisotropy field. Then, the magnetization is also perpendicular to the film, and the spectrum of SW with **k** in the plane is

$$\omega_k = \sqrt{[\gamma(\tilde{H} + 2\pi M_0 kd) + Dk^2][\gamma\tilde{H} + Dk^2]}, \quad (28)$$

where $\tilde{H} = H_0 + H_a - H_s - 4\pi M_0$.

As argued above, the damping can be neglected if the ferromagnet is in the vicinity of the phase transition. Then the critical velocity is equal to the SW phase velocity, and is minimal at $k_0 = \sqrt{\gamma \tilde{H}/D}$, while \tilde{H} should be larger than $D/\gamma \delta^2$. The minimal critical velocity is given by

$$v_c(k_0) = (4\gamma \tilde{H}D + \omega_0 d\sqrt{\gamma \tilde{H}D})^{1/2}.$$
 (29)

The above inequalities yield that $v_c(k_0)$ is restricted from below as $v_c > \sqrt{\omega_0 Dd/\delta} \approx 10^4$ cm/s. Hence, the critical current is larger than $(10^5 - 10^7)$ A/cm².

In conclusion, we have calculated the effect of an electric current on the SW spectrum in a ferromagnetic metal. We have shown that the ordinary and anomalous Hall currents lead to the reduction of the SW damping, caused by the eddy currents. At sufficiently strong currents the damping changes sign, and a SW instability develops. The critical current of the instability is determined mainly by the anomalous Hall effect, and may be much smaller than the critical current for SW excitation with spin-transfer torques.

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